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Geometric deduction of Markov's minimal forms

C.G. Lekkerkerker

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1. In the following we shall consider indefinite binary quadratic forms. Such forms have the shape

$$q = q(x) = \alpha x_1^2 + \beta x_1 x_2 + \beta x_2^2$$
 (\alpha, \beta, \beta, \gamma\text{ real});

and have positive discriminant

$$d = d(q) = \beta^2 - 4 \alpha \gamma$$
.

In this report we shall be concerned with the lower bound of |q(x)| for integral $x_1, x_2 \neq 0, 0$.

We shall denote points with integral coordinates by $u=(u_1,u_2)$, $v=(v_1,v_2)$, etc. In particular, we shall write o=(0,0). For given q, we put

(1)
$$\mu(q) = \inf_{u \neq 0} |q(u)|.$$

Further, we shall call two forms q,q' equivalent, and write q \sim q', if there is an integral unimodular transformation

$$x \rightarrow Ux = (u_{11}x_1 + u_{12}x_2, u_{21}x_1 + u_{22}x_2)$$

such that q(Ux)=q'(x). Next, we shall write $q\approx q'$ if q is equivalent with a multiple $\sigma q'$ of q'. The following relations are trivial:

(2)
$$\mu(q) = \mu(q') \text{ and } d(q) = d(q') \text{ if } q \sim q'$$

(3)
$$\mu(q)/\sqrt{d(q)} = \mu(q')/\sqrt{d(q')} \quad \text{if } q \approx q'.$$

The theorem of Markov, which we shall state below and for which we intend to give a geometric proof, gives detailed information concerning the quantity $\mu(q)/\sqrt{d(q)}$.

The geometry can be brought in as follows. Let S be the two-dimensional domain

(4)
$$S:|x_1x_2| < 1$$
,

bounded by the two orthogonal hyperbolas $x_1x_2=\pm 1$, and let Y denote the lattice of points u in the plane with integral coordinates. The domain S is left invariant under the hyperbolic rotations

(5)
$$T : x'_1 = \tau x_1, \quad x'_2 = \tau^{-1} x_2 \quad (\tau \neq 0 \text{ and real})$$

and under the reflections with respect to the coordinate axes and the lines $x_1 = \pm x_2$.

Further, if we subject Y to a nonsingular linear transformation

$$x \rightarrow Ax = (a_{11}x_1 + a_{12}x_2, a_{21}x_1 + a_{22}x_2),$$

then we get a general plane <u>lattice</u> Λ consisting of the points Au (u ϵ Y) enz. It is generated by the two points Ae,Af, where e=(1,0) and f=(0,1), and has determinant

$$d(\Lambda) = |\det A|$$
.

Now consider an arbitrary form q(x). It can be written as the product of two linear factors, say

(6)
$$q(x) = (a_{11}x_1 + a_{12}x_2)(a_{21}x_1 + a_{22}x_2);$$

if A is the matrix (a_{ij}) and \overline{q} denotes the special form $\overline{q}(x)=x_1x_2$, then (6) reads

$$q(x) = \overline{q}(Ax).$$

Suppose that μ (q) has a positive value μ . Then, by (1) and (6), each point $x\neq 0$ of the form Au satisfies $|x_1x_2| \geqslant \mu$, i.e. the lattice $\Lambda = AY$, where A satisfies (6'), has no point $\neq 0$ in $\sqrt{\mu}$ S. With the usual terminology, we say that Λ is admissible for $\sqrt{\mu}$ S. More precisely, we have

(7)
$$\inf_{x \neq 0, x \in \Lambda} |x_1 x_2| = \mu,$$

where $\mu = \mu(q)$, $\Lambda = AY$, $q(x) = \overline{q}(Ax)$, so that Λ is admissible for $\sqrt{\mu}$ S, but no longer for $\sqrt{\mu}$ 'S as $\mu \cdot \mu$.

We may denote the square root of the left hand member of (7) by

(8)
$$\mu(\Lambda) = \mu(S, \Lambda) = \inf_{x \neq 0, x \in \Lambda} |x_1 x_2|^{\frac{1}{2}}.$$

We further note that the form (6) has discriminant (det A) 2 . Then, for the lattice Λ considered above,

(9)
$$\mu(\Lambda) = \sqrt{\mu(q)}, \quad d(\Lambda) = \sqrt{d(q)}.$$

There is a correspondence between forms ${\tt q}$ and lattices ${\bm \Lambda}$. It can be expressed by

(10)
$$q(x) = \overline{q}(Ax)$$
, $\Lambda = A Y$.

But this correspondence is not one-to-one. On the other hand, any two lattices AY and AUY are identical, since Y =UY. Thus, equivalent forms correspond with the same lattice. On the other hand, the form \overline{q} is left invariant under all hyperbolic rotations T (which means that q(x) and $q(A^{-1}TAx)$ are identical for all T). The corresponding lattices are Λ =AY, Λ '=TAY. Such lattices are obtained from each other by means of a hyperbolic rotation of the plane, and one has the formulas (similar to (2)):

(11)
$$\mu(\Lambda) = \mu(\Lambda')$$
 and $d(\Lambda) = d(\Lambda')$ if $\Lambda' = T\Lambda$.

The right form of the correspondence between forms and lattices is given in our case by

(12)
$$\left\{ q_{IJ} \right\}_{U} \leftrightarrow \left\{ \Omega^{\mathcal{E}} T \Lambda \right\}_{T} \quad (\mathcal{E} = 0, 1),$$

where q and Λ are connected by (10) and $\mathbf{q}_{\mathbf{U}}$ means the form $\mathbf{q}(\mathbf{U}\mathbf{x})$.

2. We proceed to find all lattices Λ with

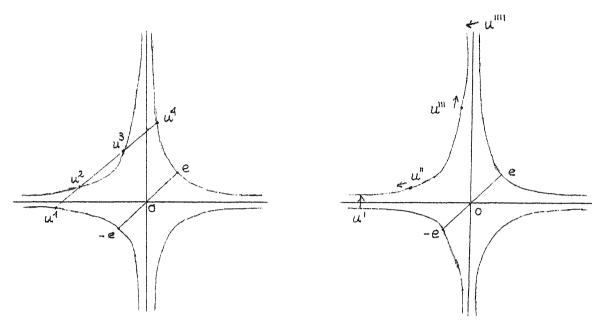
(13)
$$\mu(S, \Lambda) = 1$$
, $d(\Lambda) < 3$.

Let B denote the boundary of S, and let B_1, B_2, B_3 be the parts of B in the 1st,2nd,3rd quadrant respectively. Let x^0 be the point (1,1) on B_1 . We shall first determine the lattices Λ satisfying (13) and having a point on the boundary B. It is no restriction to suppose that $x^0 \in \Lambda$; then Λ has a basis $\{e,f\}$, with

(14)
$$e = x^{0}$$
.

A generic point u_1e+u_2f of Λ may be denoted by $u=(u_1,u_2)$; accordingly, from now on coordinates will always be taken with respect to a (suitably chosen) basis $\left\{x^0,f\right\}$ of Λ . The lattice Λ is determined completely if we know three points e,u,v of Λ on the boundary B; likewise, the corresponding quadratic form q is determined uniquely

by its values in e,u,v. We now construct a certain denumerable set of lattices and then prove that these lattices are all admissible and give all lattices satisfying our conditions. We repeat that we always take $e=x^{O}$.



The first lattice, say $\Lambda_1=A_1Y$, is such that $u^2=(-2,1)\in B_2$ and $u^3=(-1,1)\in B_2$. Put

(15)
$$q_1(x) = det(x, V_0 x), \text{ where } V_0 = \begin{pmatrix} 0 & -1 \\ 1 & 3 \end{pmatrix}.$$

Then $q_1(u) = 1,-1,-1$ for $u=e,u^2,u^3$ respectively, and so $\overline{q}(A_1x)=q_1(x)$. For arbitrary A, we have

(16)
$$\det(Ax,Ay) = \det A \cdot \det(x,y).$$

Hence, $q_1(V_0x) = q_1(x)$, i.e. V_0 is an automorphism of $q_1(x)$. Hence, $u^1 = -V_0^{-1}e = (-3,1)$ lies on B_3 and $u^4 = V_0e = (0,1)$ lies on B_1 .

The second lattice, say $\Lambda_2 = A_2 Y$, is obtained from Λ_1 by moving u^2 along B_2 until u^4 reaches B_2 . Put

(17)
$$q_2(x) = \frac{1}{2} det(x, U_0 x), \text{ where } U_0 = \begin{pmatrix} 1 & 2 \\ 2 & 5 \end{pmatrix}.$$

Then $q_2(u) = 1,-1,-1$ for $u=e,u^2,u^4$, and so $\overline{q}(A_2x)=q_2(x)$. Further, U_0 is an automorphism of $q_2(x)$, so that $-U_0^{-1}e=(-5,2)$ lies on B_3 and $U_0e=(1,2)$ lies on B_1 . As is easily verified, the matrices U_0 , V_0 satisfy the following relation, which will be important in the sequel:

(18)
$$U_0V_0 = V_0KU_0$$
, with $K = \begin{pmatrix} -1 & 6 \\ 0 & -1 \end{pmatrix}$.

The third lattice, say $\Lambda_3 = A_3 Y$, has the points $u^4 = V_0 e = (0,1)$ and $-U_0^{-1}e = (-5,2)$ on B_2 . We put

(19)
$$q_5(x) = \frac{1}{5} \det(x, U_0 V_0 x).$$

We have $q_5(e)=1$. By repeated application of (16) and (18) and by using Ke=-e we find that $q_5(V_0e)=q_5(-U_0^{-1}e)=-q_5(e)=-1$. So $\overline{q}(A_3x)=q_5(x)$. Further, U_0V_0 is an automorphism of $q_5(x)$. So we find that A_3 has a.o. the following four points on B:

(20)
$$u' = -(U_0V_0)^{-1}e, \quad u'' = -U_0^{-1}e, \quad u''' = U_0V_0e.$$

These points are connected with each other by

(21)
$$V_0 u' = u''$$
, $U_0 V_0 u'' = u'''$, $U_0 u''' = u''''$.

The above procedure can be continued indefinitely. It should be noted that Λ_1 and Λ_2 are symmetric with respect to the bisectrices of the axes, but not Λ_3 . So from Λ_3 we can obtain two different lattices, for which respectively u',u''' and u",u''' lie on B_2 . We now introduce the following notations.

 $\begin{cases} \mathcal{W}: \text{ set of pairs of integral matrices } (\dot{\mathbf{U}},\mathbf{V}) \text{ such that a) } (\dot{\mathbf{U}}_0,\mathbf{V}_0) \in \mathcal{H} \\ \text{b) if } (\mathbf{U},\mathbf{V}) \in \mathcal{H} \text{ , then } (\dot{\mathbf{U}}\mathbf{V},\mathbf{V}) \in \mathcal{H} \text{ and } (\mathbf{U},\mathbf{U}\mathbf{V}) \in \mathcal{H} \\ \text{b) if } (\mathbf{U},\mathbf{V}) \in \mathcal{H} \text{ , then } (\dot{\mathbf{U}}\mathbf{V},\mathbf{V}) \in \mathcal{H} \text{ and } (\mathbf{U},\mathbf{U}\mathbf{V}) \in \mathcal{H} \\ \text{b) if } (\mathbf{U},\mathbf{V}) \in \mathcal{H} \text{ , then } (\dot{\mathbf{U}}\mathbf{V},\mathbf{V}) \in \mathcal{H} \text{ and } (\mathbf{U},\mathbf{U}\mathbf{V}) \in \mathcal{H} \\ \text{b) if } (\mathbf{U},\mathbf{V}) \in \mathcal{H} \text{ , then } (\dot{\mathbf{U}}\mathbf{V},\mathbf{V}) \in \mathcal{H} \text{ and } (\mathbf{U},\mathbf{U}\mathbf{V}) \in \mathcal{H} \\ \text{b) if } (\mathbf{U},\mathbf{V}) \in \mathcal{H} \text{ , then } (\dot{\mathbf{U}}\mathbf{V},\mathbf{V}) \in \mathcal{H} \text{ and } (\mathbf{U},\mathbf{U}\mathbf{V}) \in \mathcal{H} \\ \text{b) if } (\mathbf{U},\mathbf{V}) \in \mathcal{H} \text{ and } \mathbf{U} \in \mathcal{H} \\ \text{b) if } (\mathbf{U},\mathbf{V}) \in \mathcal{H} \text{ and } (\mathbf{U},\mathbf{U}\mathbf{V}) \in \mathcal{H} \\ \text{b) if } (\mathbf{U},\mathbf{V}) \in \mathcal{H} \text{ and } (\mathbf{U},\mathbf{U}\mathbf{V}) \in \mathcal{H} \\ \text{b) if } (\mathbf{U},\mathbf{V}) \in \mathcal{H} \text{ and } (\mathbf{U},\mathbf{U}\mathbf{V}) \in \mathcal{H} \\ \text{b) if } (\mathbf{U},\mathbf{V}) \in \mathcal{H} \text{ and } (\mathbf{U},\mathbf{U}\mathbf{V}) \in \mathcal{H} \\ \text{c) if } (\mathbf{U},\mathbf{V}) \in \mathcal{H} \text{ and } (\mathbf{U},\mathbf{U}\mathbf{V}) \in \mathcal{H} \\ \text{c) if } (\mathbf{U},\mathbf{V}) \in \mathcal{H} \text{ and } (\mathbf{U},\mathbf{U}\mathbf{V}) \in \mathcal{H} \\ \text{c) if } (\mathbf{U},\mathbf{V}) \in \mathcal{H} \text{ and } (\mathbf{U},\mathbf{U}\mathbf{V}) \in \mathcal{H} \\ \text{c) if } (\mathbf{U},\mathbf{V}) \in \mathcal{H} \text{ and } (\mathbf{U},\mathbf{U}\mathbf{V}) \in \mathcal{H} \\ \text{c) if } (\mathbf{U},\mathbf{V}) \in \mathcal{H} \text{ and } (\mathbf{U},\mathbf{U},\mathbf{V}) \in \mathcal{H} \\ \text{c) if } (\mathbf{U},\mathbf{V}) \in \mathcal{H} \text{ and } (\mathbf{U},\mathbf{U},\mathbf{V}) \in \mathcal{H} \\ \text{c) if } (\mathbf{U},\mathbf{V}) \in \mathcal{H} \text{ and } (\mathbf{U},\mathbf{U},\mathbf{V}) \in \mathcal{H} \\ \text{c) if } (\mathbf{U},\mathbf{V}) \in \mathcal{H} \text{ and } (\mathbf{U},\mathbf{U},\mathbf{V}) \in \mathcal{H} \\ \text{c) if } (\mathbf{U},\mathbf{V}) \in \mathcal{H} \text{ and } (\mathbf{U},\mathbf{U},\mathbf{V}) \in \mathcal{H} \\ \text{c) if } (\mathbf{U},\mathbf{V}) \in \mathcal{H} \text{ and } (\mathbf{U},\mathbf{U},\mathbf{V}) \in \mathcal{H} \\ \text{c) if } (\mathbf{U},\mathbf{V}) \in \mathcal{H} \text{ and } (\mathbf{U},\mathbf{V}) \in \mathcal{H} \\ \text{c) if } (\mathbf{U},\mathbf{V}) \in \mathcal{H}$

Then, if (U,V) is a pair of $\partial\mathcal{H}$ and W is an arbitrary matrix of $|\partial\mathcal{H}|$, the following seven properties hold:

II
$$(MT)_S = -I$$

formed into -q(U,V;x) by VL

III $q(U,V;x) = \frac{1}{m} \det(x,Wx)$, where $W=(w_{i,j}) = UV$ and $m = w_{21}$ IV q(U,V;x) is invariant under the transformation UV and is trans-

V Λ (U,V) has four points u',u",u",u" on B3,B2,B2,B4 respectively, such that

(22)
$$UVu' = -e, Uu'' = -e, Ve=u''', UVe = u''''$$

(23)
$$Vu' = u'', \quad UVu'' = u''', \quad Uu''' = u''''$$

VI W has the form $\binom{k}{m} \frac{1}{3m-k}$, so that the corresponding form $\frac{1}{m} \det(x, Wx) = \frac{1}{m} \{mx_1^2 + (3m-2k)x_1x_2 - 1x_2^2\} = q_m(x)$, say, has discriminant $d_m = d(q_m) = 9.4m \cdot 2$

VII the lattices in $\mathcal L$ are admissible for S.

Proof. Properties I and II are easily proved by induction. Property XII can be verified as follows:

$$det(e,We) = m,$$
 $det(U^{-1}e,UVU^{-1}e) = det(U^{-1}e,VKe) = -det(e,UVe) = -m,$
 $det(Ve,UVVe) = det(e,KUVe) = -m.$

The first clause in IV is a consequence of III and the second one is proved as follows:

$$det(VLx,UVVLx) = det(VLx,-VL^2UVLx) = det(x,-LUVLx)$$
$$= det(UVx,-(UVL)^2x) = det(UVx,x) = -det(x,UVx).$$

Property V is proved by induction as follows. We saw already that V holds for $\Lambda_3 = \Lambda(U,V)$. Suppose V holds for $\Lambda(U,V)$, and consider $\Lambda(UV,V)$. Let $v^{(1)}$ (1 \leq i \leq 4) be the points with

 $UVVv^{\dagger} = -e$, $UVV^{\dagger\dagger} = -e$, $Ve=v^{\dagger\dagger\dagger}$, $UVVe=v^{\dagger\dagger\dagger\dagger}$.

Then v''=u', v'''=u''', and so

$$Vv' = -(UV)^{-1} \circ = v''$$
, $UVVv'' = UVVu' = UVu'' = u'''=v'''$, $UVv''' = UVVe = v''''$.

Further, by IV and the proof of III, the $v^{(i)}$ lie on B. Hence V holds for $\Lambda(UV,V)$. Similarly for (U,UV).

As for the proof of VI, let W=UV and let the $u^{(i)}$ be given by (22). By II, $(WL)^2e=-e$ or $LWLe=-W^{-1}e$, i.e. Lu''''=u'. Now u''''=We has second coordinate $u_{21}=m$, and so u'''' has the form (k,m). Then u'=Lu''''=(k-3m,m). Then, since u'''''=We and $u'=W^{-1}e$, W has the form stated, Since det W=1, we have

$$(24) k^2 + 1 = m(3k-1).$$

Finally, $d_m = m^{-2} \{ (3m-2k)^2 + 41m \} = 9-4m^{-2}$. Property VI also holds for $W = U_0 \cdot V_0$.

Property VII = lemma 10 in [2], chapter II; the proof is based on IV and VI.

It is now easy to prove the following Theorem 1. The lattices Λ satisfying (13) and passing through x^0 are just given by the lattices in $\mathcal K$.

<u>Proof.</u> Let Λ be such a lattice. Let G_1 be the set of points <u>outside</u> S lying in the 1st or 3rd quadrant, and let G_2 denote the set of points outside S in the 2nd quadrant. We may suppose that (-2,1) and (-1,1) belong to G_2 (see the figure). If (-3,1) and (0,1) belong to G_1 , then necessarily $\Lambda = \Lambda_1$. If not, then for reasons of symmetry we may suppose that (0,1) \mathcal{E}_2 . Then necessarily $\Lambda = \Lambda_2$, if (-5,2) \mathcal{E}_3 and (1,2) \mathcal{E}_3 (see figure). If not, then we may suppose that (-5,2) \mathcal{E}_3 and \mathcal{E}_3 . Then \mathcal{E}_3 and \mathcal{E}_3

We now use the following property, which is geometrically clear: if Λ satisfies our conditions, if $u^{(i)}$ are defined by (22) and if u'', u''' lie in G_2 and u', u'''' in G_1 , then necessarily $\Lambda = \Lambda(U, V)$. Suppose that, for some pair $(U, V) \in \mathcal{M}$,

(25)
$$-U^{-1}e \in G_2$$
, $Ve \in G_2$.

Then there are four possibilities:

- a) $-(U^{\vee})^{-1}e$, $U^{\vee}e \in G_1$; then $\Lambda = \Lambda(U, V)$
- b) $-(UV)^{-1}e$, $\in G_2$; then (25) holds for the pair (UV,V)
- c) UVe \mbox{G}_{2} ; then (25) holds for the pair (U,UV)
- d) -(UV)⁻¹, UVe ϵG_2 ; it is easy to prove that in this case $d(\Lambda) > 3$.

We now note that $d_m=9-4m^{-2}$ and that m is a positive integer increasing for each step. It follows that after finitely many steps the possibility a) occurs, since $d(\Lambda) < 3$. This proves theorem 1.

In order to solve our problem completely we must consider lattices which do not have a point on B. But here we have the following

Lemma. Each lattice satisfying (13) has points on B.

The proof of this lemma may be sketched as follows. Let Λ be any lattice with $\mathcal{L}\iota(S,\Lambda)=1$, which does not have any point on the boundary. Then there is a sequence of points $x^r(r=1,2,...)$ of

with $|\overline{q}(x^r)| \to 1$. Suppose $\overline{q}(x^r) \to 1$. By applying suitable hyperbolic rotations T_r we get a sequence of lattices $\Lambda_r = T_r \Lambda$ with $\mathcal{M}(S, \Lambda_r) = 1$ $(r = 1, 2, \ldots)$, $\Lambda_r \ni y^r$, $y^r \to x^0$. A suitable subsequence of the sequence $\{\Lambda_r\}$ converges to some lattice $\overline{\Lambda}$. This lattice $\overline{\Lambda}$ contains the point x^0 and has determinant $d(\overline{\Lambda}) = d(\Lambda)$. Further, each point of $\overline{\Lambda}$ is the limit of a point of Λ_r and so $\overline{\Lambda}$ is admissible for S. Hence, by theorem 1, if Λ satisfies (13), then $\overline{\Lambda}$ belongs to the set \mathcal{L} . Finally, using the corresponding automorphism W, one can find a neighbourhood N of $\overline{\Lambda}$ and a positive number \overline{J} with the following property:

(26) if $\Lambda' \in \mathbb{N}$ and Λ' is not homothetic with $\overline{\Lambda}$, then $(S, \Lambda') \not\sim 1 - \eth$

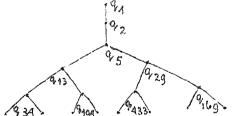
(see theorem I in [2], chapter II). This contradicts the properties of the $\Lambda_{\rm p}$, and so proves the lemma.

The lattices Λ in $\mathcal L$ have points on B_1 as well as B_2 . Hence theorem 1 and the lemma together give the following Theorem 2. Each lattice Λ ! with $\mu(S, \Lambda)=1$, $d(\Lambda)<3$ is of the form $\Lambda'=T\Lambda$, where T is a hyperbolic rotation of S and $\Lambda \in \mathcal K$.

This theorem can immediately be put in the following arithmetic form:

Theorem 2'. Let q=q(x) be an indefinite binary quadratic form, of discriminant d. Then $\mu(q) > \frac{1}{3} \sqrt{d}$, if and only if $q \approx q_m = \frac{1}{m} \det(x, Wx)$ for some $W \in |\partial \mathcal{T}| (m=w_{21})$. Further, $\mu(q) = \sqrt{d/d_m}$, with $d_m = 9-4m^{-2}$, if $q \approx q_m$.

The pairs (U,V), hence also the forms $\boldsymbol{q}_{m},$ can be represented by a genealogical tree (see figure). The numbers m associated with



three matrices U,V,W=UV, say m_1,m_2,m , satisfy the famous equation of <u>Markov</u>:

$$(27) \quad m_1^2 + m_2^2 + m^2 = 3m_1 m_2 m.$$

This relation is easily proved by induction. Cohn deduces it from property I and a general relation for the traces of 2×2 -matrices. As is well known, one can deduce from theorem 2' a corresponding theorem for the approximation of inationals by rationals. Final remark. Probably the method of this report can be extended to the more general domain $1 \times x_1 \times x_2 \times k$ (k a positive integer).

However, even the second minimum of this region is not yet known (see $\begin{bmatrix} 4 \end{bmatrix}$).

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